



QA/QC of ALCs within ACTRIS-CARS and CCRES – Dark measurements

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CARS-ALC instrument testbed



CARS-ALC-LMU

Vaisala			Campbell Scientific	Lufft	
CL31	CL51	CL61	SkyVUEPRO	CHM15kx	CHM8k
unsi		William	Burner and a second	CHM 15kx	Lum CHM 8k
operation	operation	operation	operation	Gets LOM replacement	Gets LOM replacement

CARS-ALC-DWD

DROPLET	Lufft		
MiniMPL	CHM15k	CHM8k	
	CHM 15 kx	ELLUIT CHAN BA	
operation	operation	operation	





CARS-ALC instrument testbed



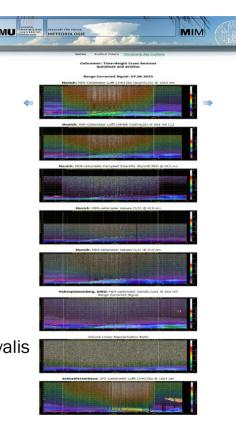
CARS-ALC unit instruments

Setup of automatic data processing and data format harmonization

- → Easier monitoring of housekeeping data
- → Easier data processing and analysis
- → Easier data and algorithm exchange with ALC community

Processing steps:

- Creation of daily files in raw output
- Conversion to Level 0/1 data format with raw2L1 tool developed within the ALC community (https://gitlab.in2p3.fr/ipsl/sirta/raw2l1)
- Creation of quicklooks for all LMU-ceilometers which are available at www.meteorologie.lmu.de/DokuWiki/doku.php?id=arbeitsgruppen:lidar:quicklooks_yalis
- First calibration measurements
 - → Dark measurements





RAW2L1 tool for data harmonization



Updates provided for RAW2L - need to be implemented in main branch

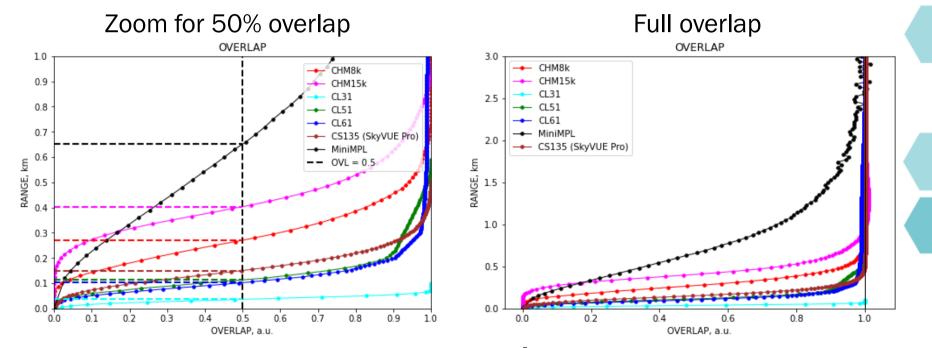
CL61	 Updated reader for firmware 1.2.7: Monitoring and HKD data were saved in netCDF attributes in FW1.1.0 → Temporal resolution was dependent on "profiles per file" parameter → In FW 1.2.7 as netCDF groups New parameters available (e.g. range resolution, transmitter_enclosure_temperature, overlap function) Prefixed HKD variables with hkd_ and status variables with status_
CHM8k	 Wrote a reader for Lufft CHM8k since it has several differences compared to CHM15k format
CHM15k	Updated reader for backwards compatibility down to FW 0.1109
CS135/SkyVUEPRO	 Updated an issue which prevented processing in case of alerts



ALC Overlap functions



Overlap functions from CARS-ALC ceilometers provided by manufacturer



Overlap functions still have to be investigated \rightarrow apply temperature correction (Hervo et al.) to existing overlap function



Regular dark measurements

- How variable are the DMs over time?
- Is a correction needed for every instrument?

Monostatic configuration	Bistatic configuration
Vaisala CL31 Vaisala CL51 Vaisala CL61 Campbell SkyVUE Pro	Lufft CHM8k Lufft CHM15k(x)
Dark measurement with optical terminatin hood from Vaisala - CL31/CL51 version	Dark measurement with telescope covered - e.g. cardboard





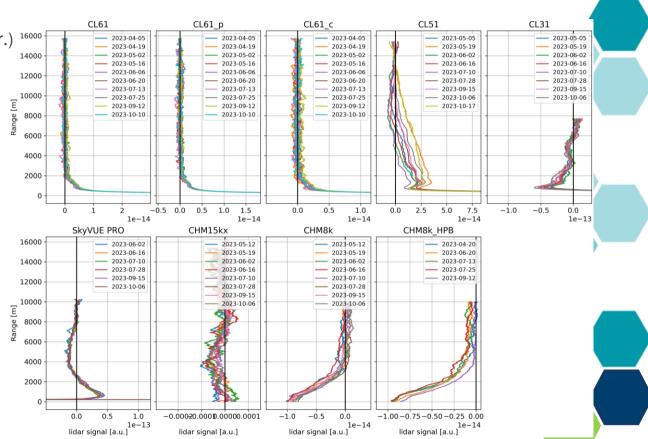


- CL61 version



Time series of DMs

- Input: Attenuated Bsc (calibrated, r2, OVL-corr.)
- Range correction removed
- Overlap function correction removed
- CL61: stable around zero above 2 km
 - strong signal increase below
- **CL51:** very variable over time and height
 - strong signal increase in near range
- **CL31:** stable over time but not height
 - strong signal increase in near range
- **SkyVUE PRO:** stable over time but not height
 - strong signal increase in NR
- **CHM15kx:** varying around zero → stable
- CHM8k: almost stable above 3-4 km
 - signal decrease below







What is the signal strength of the DM compared to normal measurements?

- Attenuated backscatter (no CHM15kx data)
- Overlap function correction not removed
- Same scale for x-axis

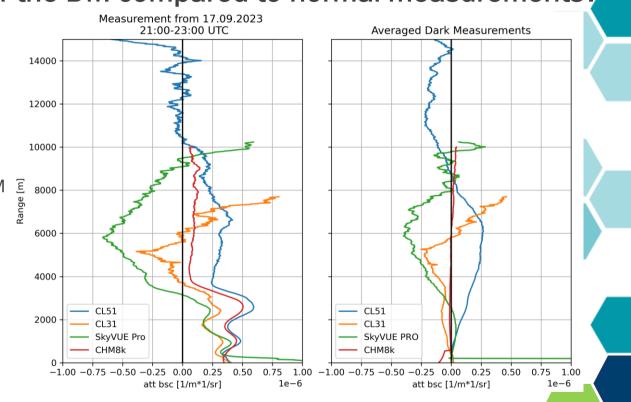
CL51: - signal strength of DM not negligible

CL31: - above 4 km with signal peaks in the DM - not negligible

SkyVUE PRO: - strong negative peak between 3 and around 8 km

- not negligible

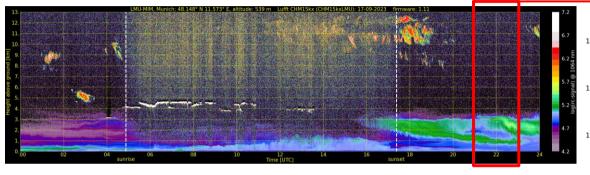
CHM8k: - DM signal strength much lower than normal profile measurement





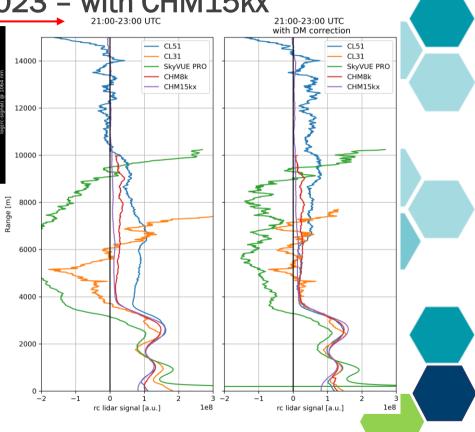


Application of a DM correction on 17.09.2023 – with CHM15kx



Saharan dust layer arriving in the evening

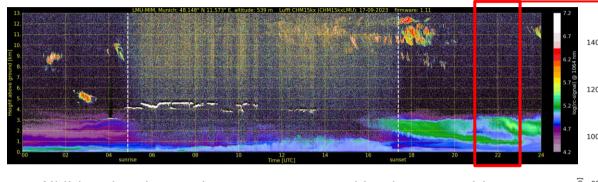
- All lidar signals are fitted to the CHM15kx which is not calibrated
 → no attenuated backscatter
- Without DC-correction, larger deviations are visible for CL31, CL51 and SkyVUE PRO
- Signal improvements are achieved with the DC-correction
- However, still strong deviations for CL51 and SkyVUE PRO





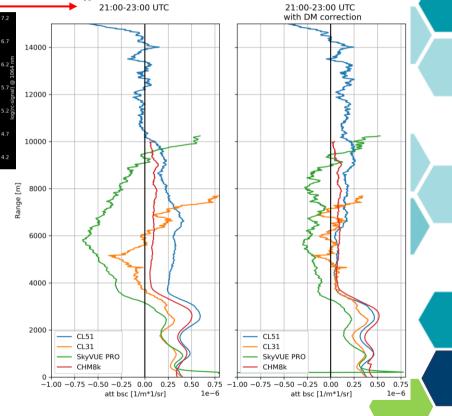


Application of a DC correction on 17.09.2023 - "calibrated instruments"



 All lidar signals are shown as attenuated backscatter with manufacturer calibration

- Without DC-correction, larger deviations are visible for CL31, CL51 and SkyVUE PRO
- Signal improvements are achieved with the DM-correction
- Still strong deviations between the instruments as shown one slide before
- Since profiles are not fitted, lidar calibration can be wrong as well

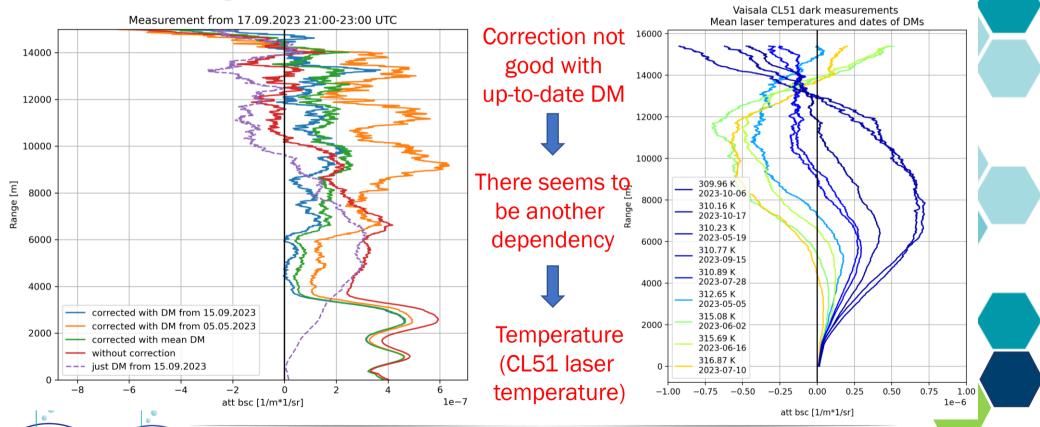




CCRES



CL51 with stronger fluctuations between DMs \rightarrow use most up-to-date DM?

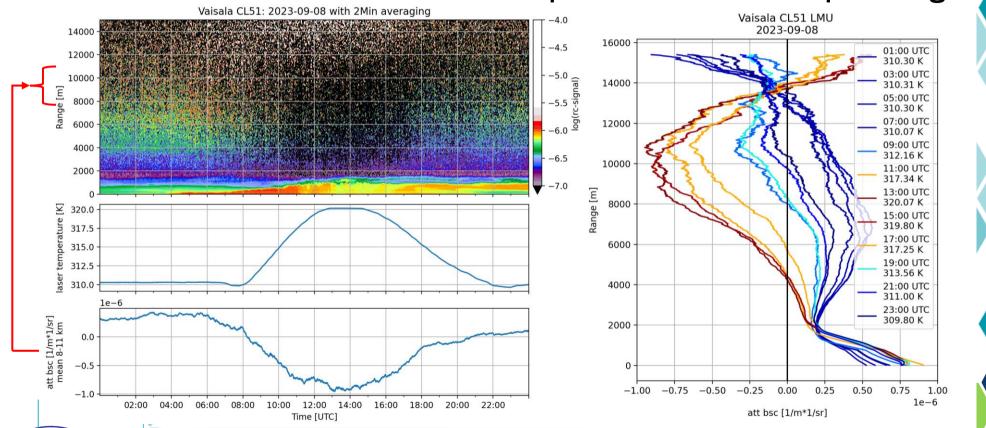


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CARS

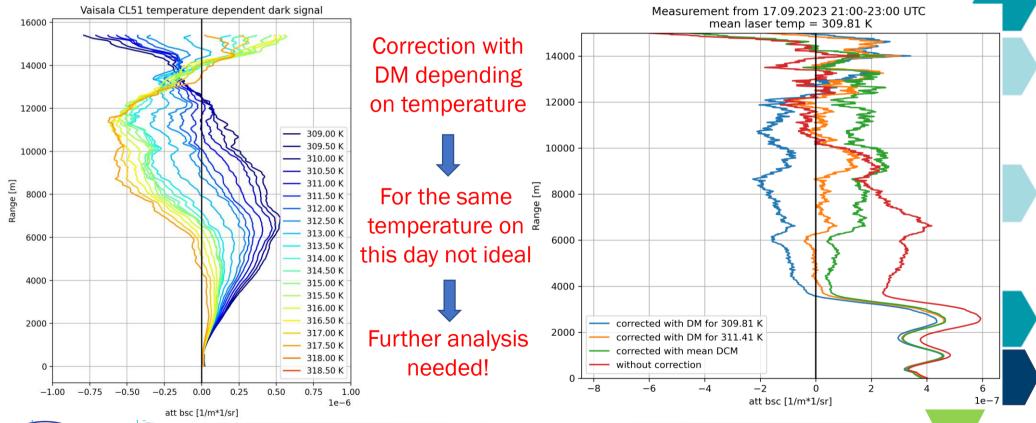


CL51 measurement on 08.09.2023: temperature $\leftarrow \rightarrow$ atmosphere signal





Possible DM correction for CL51 – Lookup table with profile for different T



Telecover test for ALCs

First measurements with telecover test for ALCs

Experimental method to reveal distance of full overlap without the assumption of a well-mixed boundary layer

Can be applied for bi-axial ALCs (Lufft CHM15k and CHM8k)

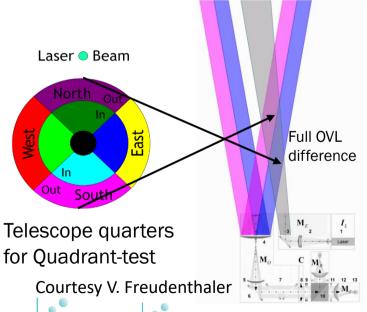




Plate for Lufft ALC

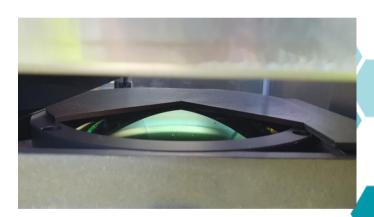


Plate on CHM8k telescope



Summary

- All instruments from CARS-ALC are now in operation
 - → Gain experience on the different instruments and apply QC/QA procedures
- RAW2L1 is used to harmonize data
 - → updated several readers
- Manufacturers overlap functions are currently used for processing
 - → determine own overlap functions
- Regular dark measurements to check stability of the instruments
 - → at the moment only the CL51 shows stronger temporal/temperature dependent variability
 - → further analysis is needed to understand this effect in order to correct for it
 - → important for aerosol profiling
- First tests with telecover measurements were performed but need further investigation









